## STUDENT QUIZ

## **QUIZ** / Wheel Size Matters - Rotation

| NAME |  |                                | DATE                       | CLASS PERIOD                |  |  |
|------|--|--------------------------------|----------------------------|-----------------------------|--|--|
|      | Put a ch   | heck in the O next to the      | correct answer.            |                             |  |  |
|      | 1. How does the modified Squarebot differ from the original Squarebot? |                                |                            |                             |  |  |
|      |  | o The modified Squareb         | ot is battery-powered.     |                             |  |  |
|      |  | o The power setting for        | the modified Squarebot     | was increased.              |  |  |
|      |  | o The gears for the fi         | ont wheels were rem        | noved on the modified       |  |  |
|      | <u>Squ</u>   | larebot.                       | a maalifiad Causanah at uu |                             |  |  |
|      |  | o The front wheels on th       | e modified Squarebot w     | ere replaced by larger whee |  |  |
|      | 2. Wha   | at is kept constant in this in | vestigation?               |                             |  |  |
|      |  | o Wheel size                   |                            |                             |  |  |
|      |  | o Type of robot                |                            |                             |  |  |
|      |  | o The distance the robo        | t travels.                 |                             |  |  |
|      |  | o Rotations of the mo          | otor axles.                |                             |  |  |
|      | 3. Whie  | ch variable is the dependen    | t in this investigation?   |                             |  |  |
|      |  | o The distance the ro          | bot travels                |                             |  |  |
|      |  | o Rotations of the moto        | r axles                    |                             |  |  |
|      |  | o Wheel size                   |                            |                             |  |  |
|      |  | o Type of robot                |                            |                             |  |  |
|      | 4. Wha   | at are systematic errors?      |                            |                             |  |  |
|      |  | o Errors that affect data      | different ways at differe  | nt times                    |  |  |
|      |  | o Errors that are caused       | l by human judgments       |                             |  |  |
|      |  | o Errors that we are una       | ble to detect              |                             |  |  |
|      |  | o Errors that always           | affect data the same       | way                         |  |  |
|      | 5. Wha   | at are random errors?          |                            |                             |  |  |
|      |  | o Errors that always affe      | ect data the same way      |                             |  |  |
|      |  | o Errors that are caused       | l by human judgments       |                             |  |  |
|      |  | o Errors that affect of        | ata different ways at      | different times             |  |  |
|      |  | o Errors that we are una       | ble to detect              |                             |  |  |
|      | 6. Whie  | ch of the following would m    | ost likely be a systemati  | ic error?                   |  |  |
|      |  | o Measuring the distance       | e the robot travels        |                             |  |  |
|      |  | o Friction                     |                            |                             |  |  |
|      |  | o Wheel slippage               |                            |                             |  |  |
|      |  | o None of the above, sir       | nce they are all random    |                             |  |  |

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|------|-----|--|-------------------------------|--------------------|--|--|
|      | 7.  | 7. Interpolation of data values means predicting a new value   |                               |                    |  |  |
|      |     | o between existing values  |                               |                    |  |  |
|      |     | o beyond existing values   |                               |                    |  |  |
|      |     | o from a new data set  |                               |                    |  |  |
|      |     | o none of the above  |                               |                    |  |  |
|      | 8.  | Extrapolation of data values means predic  | ting a new value;             | <u>*</u>           |  |  |
|      |     | o between existing values  |                               |                    |  |  |
|      |     | o from a new data set  |                               |                    |  |  |
|      |     | o beyond existing values   |                               |                    |  |  |
|      |     | o none of the above  |                               |                    |  |  |
|      | 9.  | Given the following five distances measur<br>distance: 43.8in., 47.2 in., 41.1 in., 44.5 in.,                                  | ed in inches, cal<br>42.6 in. | culate the average |  |  |
|      |     | o 219.2 in.  |                               |                    |  |  |
|      |     | <u>o 43.84 in.</u>   |                               |                    |  |  |
|      |     | o 45.9 in.   |                               |                    |  |  |
|      |     | o 42.6 in.   |                               |                    |  |  |
|      | 10. | Convert 47.8 in. to centimeters.   |                               |                    |  |  |
|      |     | o 18.8 cm.   |                               |                    |  |  |
|      |     | o 12.1 cm.   |                               |                    |  |  |
|      |     | o 188.1 cm.  |                               |                    |  |  |
|      |     | <u>o 121.4 cm.</u>   |                               |                    |  |  |
|      | 11. | 11. Given the plot shown below (Figure 1), about how far would a wheel with a diameter of 7in. travel in five rotations?       |                               |                    |  |  |
|      |     | o 40 in.   |                               |                    |  |  |
|      |     | <u>o 55 in.</u>  |                               |                    |  |  |
|      |     | o 70 in.   |                               |                    |  |  |
|      |     | o 100 in.  |                               |                    |  |  |
|      | 12. | 12. Given the plot shown below (Figure 1), what is the approximate diameter of a wheel that traveled 110in. in five rotations? |                               |                    |  |  |
|      |     | <u>o 17 in.</u>  |                               |                    |  |  |
|      |     | o 13 in.   |                               |                    |  |  |
|      |     | o 7 in.  |                               |                    |  |  |
|      |     | o 110 in.  |                               |                    |  |  |
|      |     |  |                               |                    |  |  |
|      |     |  |                               |                    |  |  |
|      |     |  |                               |                    |  |  |
|      |     |  |                               |                    |  |  |

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